

GUIDE SYSTEM FOR CONTROLLED MANIPULATION OF SURGICAL
INSTRUMENTS

ABSTRACT OF THE DISCLOSURE

5 A guide system (20) enables controlled manipulation of a
grasping forceps (22) relative to a cutter stapler (24). The
guide system (20) includes a body (26) for surrounding a shaft
(40) of the stapler (24), with a stapler head (42) and a
stapler actuator (44) extending from opposing ends of the body
10 (26). An articulating member (28) is in longitudinal alignment
with the body (26) and is selectively moveable to cause an
extension portion (64) of the member (28) to move to an
extended position (82) transverse from the body. A sleeve
(30), coupled to the extension portion (64), retains an
15 elongate flexible member (34) of the grasping forceps (22).
Movement of the extension portion (64) causes corresponding
movement of the sleeve (30) to adjust a working angle (72)
between a grasper end (36) of the grasping forceps (22) and the
stapler head (42).